

Matérn Gaussian Processes on Riemannian manifolds

Viacheslav Borovitskiy (Slava)

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Mathematics and Computer Science Department, St. Petersburg University
St. Petersburg Department of Steklov Mathematical Institute

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Viacheslav*
Borovitskiy



Alexander*
Terenin



Peter*
Mostowsky



Marc
Deisenroth



St Petersburg
University

Imperial College
London



UCL

* Equal contribution

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Matérn kernels

Defining Matérn kernels on compact Riemannian manifolds

Solving for Matérn kernels on compact Riemannian manifolds

Toy examples

Conclusion

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Gaussian processes

Gaussian processes (GPs) are distributions over functions.

They are used as non-parametric priors for machine learning tasks.

A Gaussian process is determined by its mean and covariance functions:

$$f \sim GP(m(\cdot), k(\cdot, \cdot)),$$

where

- $m(\cdot) : \mathbb{R}^d \rightarrow \mathbb{R}$ is any function,
- $k(\cdot, \cdot) : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ is a positive-definite function (kernel).

This means that for any $X = (x_1, \dots, x_N)^\top$ the joint distribution of the vector $f(X) = (f(x_1), \dots, f(x_N))^\top$ is

$$f(X) \sim N(m_X, K_{XX}),$$

with

$$\begin{aligned}(K_{XX})_{ij} &:= k(x_i, x_j), \\ m_X &:= (m(x_1), \dots, m(x_N))^\top.\end{aligned}$$

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Gaussian process regression

Consider a set of observations (x_n, y_n) , $x_n \in \mathbb{R}^d$, $y_n \in \mathbb{R}$, $n = 1, \dots, N$.

Assume a Gaussian process prior on $f \sim GP(0, k)$ and the Gaussian likelihood parameterized by the noise σ^2

$$p(Y | f(X)) = N(f(X), \sigma^2 I)$$

Then we can compute the posterior:

$$f(\cdot) | Y \sim GP(\hat{m}(\cdot), \hat{k}(\cdot, \cdot))$$

with

$$\begin{aligned}\hat{m}(\cdot) &= K_{*X} (K_{XX} + \sigma^2 I)^{-1} Y, \\ \hat{k}(*, *') &= k(*, *') - K_{*X} \underbrace{(K_{XX} + \sigma^2 I)^{-1}}_{N \times N \text{ matrix}} K_{X*'}.\end{aligned}$$

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Visual guide to Gaussian process regression



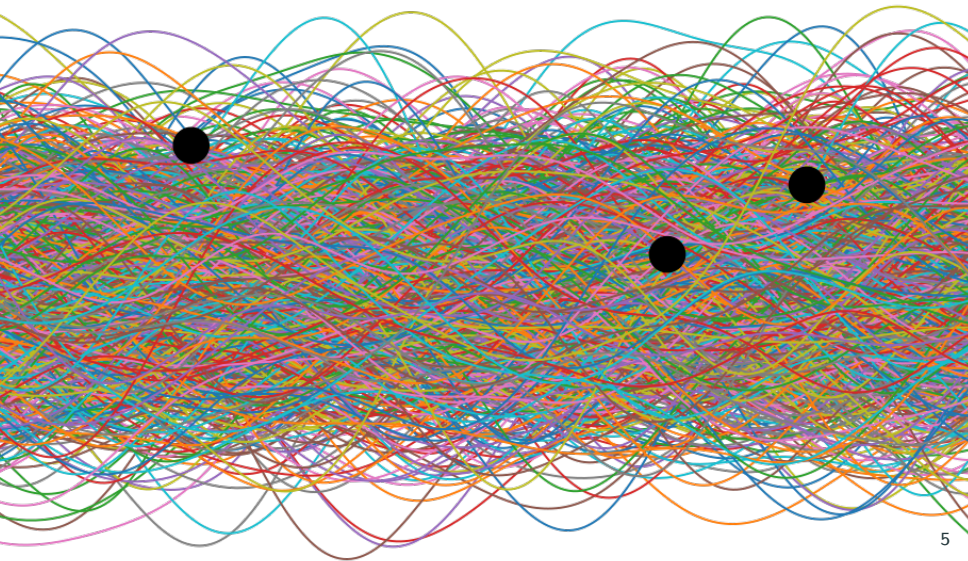
Visual guide to Gaussian process regression



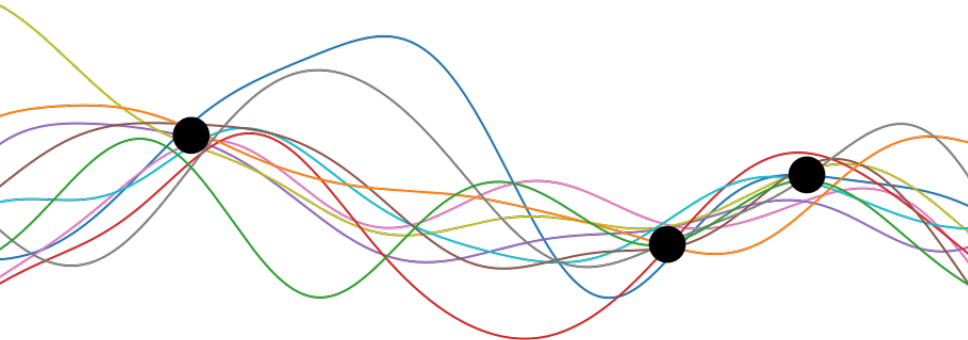
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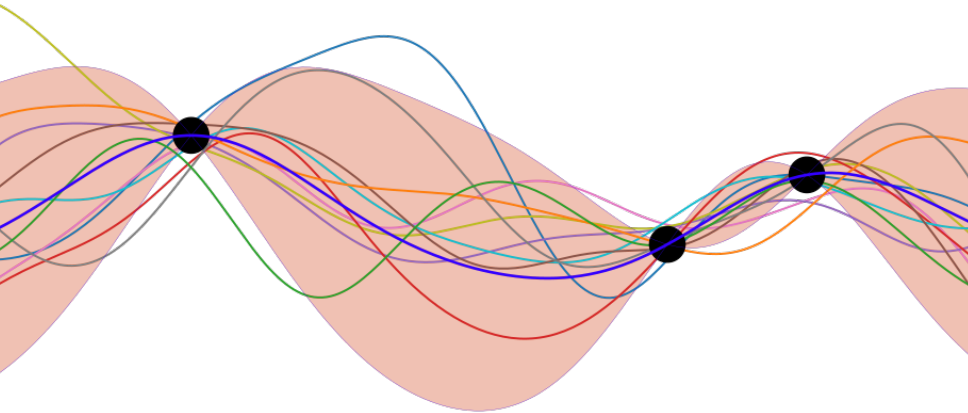
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Visual guide to Gaussian process regression



Picking the prior

Pick a parametric family $\{k_\theta(\cdot, \cdot)\}_{\theta \in \Theta}$.

Maximize log likelihood over θ :

$$\log p(Y) = -\frac{1}{2} Y^\top (K_{XX} + \sigma^2 I)^{-1} Y - \frac{1}{2} \log |K_{XX} + \sigma^2 I| - \frac{n}{2} \log 2\pi$$

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Matérn kernels

This is the most frequently used parametric family of kernels for GPs.

$$k(x, x') = \sigma^2 \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\sqrt{2\nu} \frac{\|x - x'\|}{\kappa} \right)^\nu K_\nu \left(\sqrt{2\nu} \frac{\|x - x'\|}{\kappa} \right)$$

σ^2 : variance κ : length scale ν : smoothness

$\nu \rightarrow \infty$: recovers square exponential kernel

We have $k : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$. This defines GPs $f : \mathbb{R}^d \rightarrow \mathbb{R}$.

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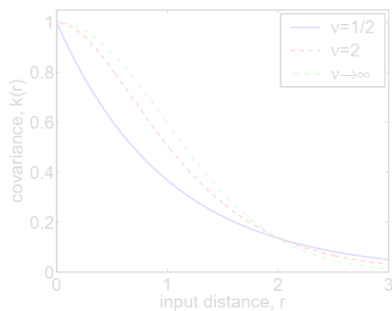
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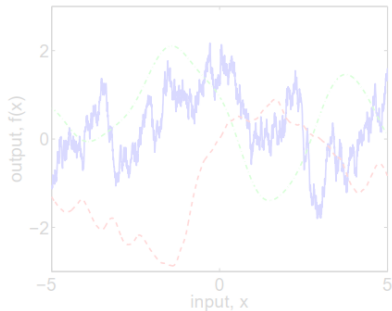
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Visual guide to Matérn kernels



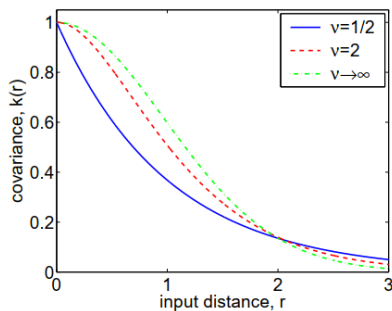
(a)



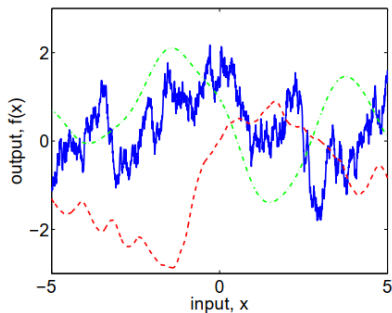
(b)

(a) Matérn kernels as functions of $\|x - x'\|$; (b) GP sample paths

Visual guide to Matérn kernels



(a)



(b)

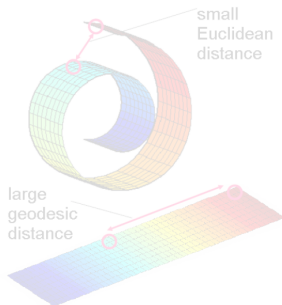
(a) Matérn kernels as functions of $\|x - x'\|$; (b) GP sample paths

Defining Matérn kernels on compact Riemannian manifolds

How to define analogous parametric families on a manifold?

First try: embed a manifold into Euclidean space \mathbb{R}^d and take Matérn kernels from this ambient space.

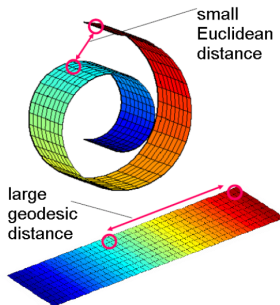
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How to define analogous parametric families on a manifold?

Second try: substitute geodesic distance $d_M(x, x')$ instead of $\|x - x'\|$ into the formula for Matérn kernels.

Surprisingly, this doesn't work, the kernel generally fails to be positive-definite (Feragen et al.):



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Geodesic Exponential Kernels: When Curvature and Linearity Conflict

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aasa@diku.dk

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DIKU, University of Copenhagen
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Matérn SPDE

In 60's Whittle have shown that a GP with Matérn kernel over \mathbb{R}^d satisfies this particular SPDE:

$$\left(\frac{2\nu}{\kappa^2} - \Delta\right)^{\frac{d}{4} + \frac{\nu}{2}} f = \mathcal{W}.$$

Here \mathcal{W} is the Gaussian white noise.

The meaning of the left hand side:

$$\left(\frac{2\nu}{\kappa^2} - \Delta\right)^p f = \mathcal{F}^{-1} \left(\frac{2\nu}{\kappa^2} + |\zeta|^2\right)^p \mathcal{F}f(\zeta)$$

where \mathcal{F} is the Fourier transform.

This generalizes well to the Riemannian setting:

1. Δ becomes the Laplace–Beltrami operator,
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The problem is the implicit nature of this definition.

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Solving for Matérn kernels on compact Riemannian manifolds

Laplace–Beltrami operator

Consider a *compact* Riemannian manifold (M, d) and denote the Laplace–Beltrami operator on (M, d) by $\Delta : C^\infty(M) \mapsto L^2(M)$.

Theorem (Sturm–Liouville decomposition)

There exists an orthonormal basis $(f_n)_{n \in \mathbb{Z}_+}$ of the space $L^2(M)$, and a sequence of non-negative numbers $0 = \lambda_0 < \lambda_1 \leq \lambda_n \leq \dots$ such that

$$-\Delta f_n = \lambda_n f_n$$

and

$$-\Delta f = \sum_{n \geq 0} \lambda_n \langle f, f_n \rangle f_n$$

Imagine f_n as a substitute for sines and cosines in Fourier series.

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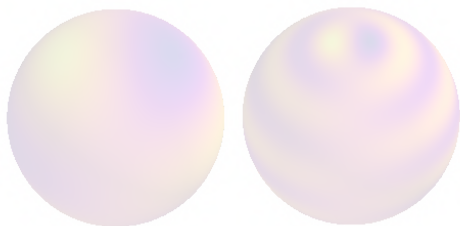
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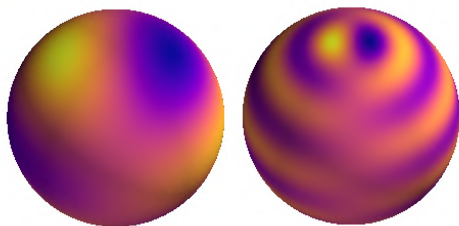
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Visual guide to Laplace–Beltrami eigenfunctions



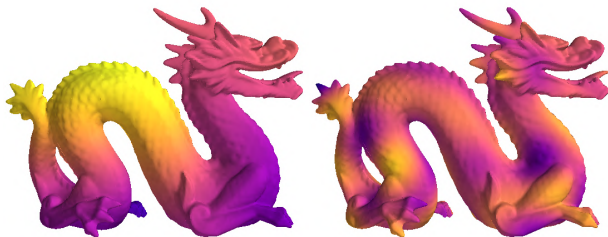
Sample eigenfunction on the sphere

Visual guide to Laplace–Beltrami eigenfunctions



Sample eigenfunction on the sphere

Visual guide to Laplace–Beltrami eigenfunctions



Sample eigenfunction on the dragon

Solving Matérn SPDE on a compact Riemannian manifold

With

$$-\Delta f = \sum_{n \geq 0} \lambda_n \langle f, f_n \rangle f_n$$

it is natural to define

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Somewhat informally, we can represent the Gaussian white noise by

$$\mathcal{W} = \sum_{n \geq 0} w_n f_n, \quad w_n \sim N(0, 1) \text{ (i.i.d.)}$$

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Solving Matérn SPDE on a compact Riemannian manifold

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Continuing our informal computation, we get

$$\left(\frac{2\nu}{\kappa^2} + \lambda_n \right)^p \langle f, f_n \rangle = w_n \quad \implies \quad \langle f, f_n \rangle = \left(\frac{2\nu}{\kappa^2} + \lambda_n \right)^{-p} w_n$$

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This is the formula for the Matérn kernel!

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Riemannian Matérn kernels on compact spaces

Matérn kernel:
$$k_\nu(x, x') = \frac{\sigma^2}{C_\nu} \sum_{n=0}^{\infty} \left(\frac{2\nu}{\kappa^2} - \lambda_n \right)^{\nu - \frac{d}{2}} f_n(x) f_n(x')$$

λ_n, f_n are Laplace–Beltrami eigenpairs (known analytically or approximated numerically).

This is the Karhunen–Loève type expansion: $f_n(\cdot)$ are analogous to Fourier features.



Figure: values of Matérn kernel $k_{1/2}(x, \cdot)$. x is marked with a red dot.

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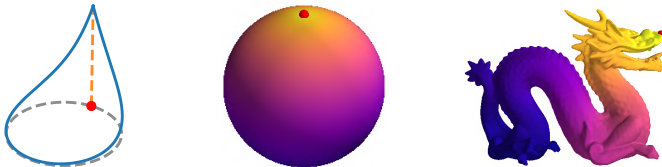


Figure: values of Matérn kernel $k_{1/2}(x, \cdot)$. x is marked with a red dot.

Toy examples

A Gaussian process regression problem on the dragon



(a) Ground truth



(b) Posterior mean



(c) Standard deviation



(d) A sample path

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(b) Posterior mean

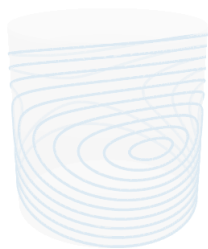


(c) Standard deviation

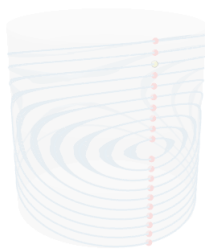


(d) A sample path

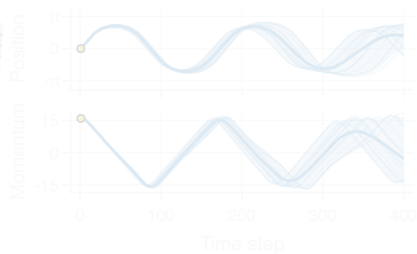
Pendulum dynamics



(a) Ground truth

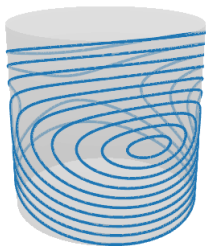


(b) 95%-confidence

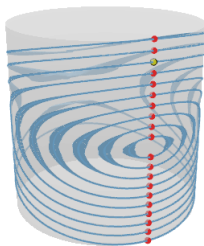


(c) Trajectories

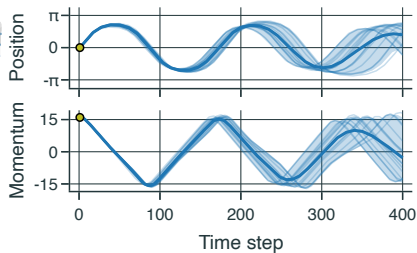
Pendulum dynamics



(a) Ground truth



(b) 95%-confidence



(c) Trajectories

Conclusion

Why useful:

- if you know Laplace–Beltrami eigenpairs, you have explicit formulas for Matérn kernels,
- these kernels can be used in the usual GP framework including sparse regression, Fourier feature sampling etc.

What's next:

- experiments with Bayesian optimization,
- vector fields,
- also...

Matérn Gaussian Processes on Graphs

Viacheslav Borovitskiy^{*1, 5}
Peter Mostowsky¹

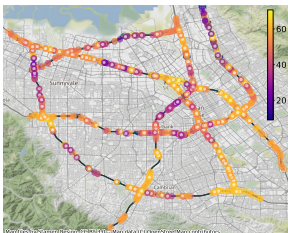
Iskander Azangulov^{*1}
Marc Peter Deisenroth³

Alexander Terenin^{*2}
Nicolas Durrande⁴

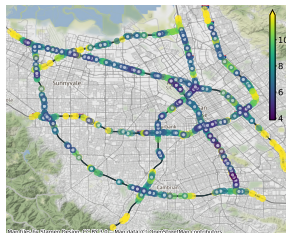
¹St. Petersburg State University ²Imperial College London ³University College London ⁴Secondmind

⁵St. Petersburg Department of Steklov Mathematical Institute of Russian Academy of Sciences

In review for AISTATS 2021



(a) Mean



(b) Standard deviation

Concluding remarks

Thank you for your attention!

Special thanks to Peter Mostowsky for his help with these slides.

Blog post:

<https://sml-group.cc/blog/2020-gp-sampling/>

GitHub:

<https://github.com/spbu-math-cs/Riemannian-Gaussian-Processes>

Feel free to email me via viacheslav.borovitskiy@gmail.com



St Petersburg
University

Imperial College
London



UCL